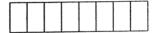
國立臺北科技大學

九十六學年第二學期電機系博士班資格考試

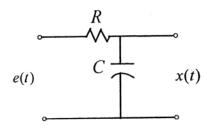
數位控制理論與應用試題

生證號碼

第一頁 共一頁



- 本試題共【5】題,配分共100分。
 請按順序標明題號作答,不必抄題。
 全部答案均須答在試卷答案欄內,否則不予計分。
- 1. (20%) Consider the RC circuit shown in following figure. Derive the difference equation describing the dynamics of the circuit when the input voltage applied is piecewise constant, or e(t) = e(kT), $kT \le t < (k+1)T$.



- 2. Consider the system with pulse transfer function: $\frac{Y(z)}{U(z)} = \frac{z^2 + 7z + 9}{z^2 + 5z + 6}$
 - (1) (10%) please find the corresponding state-space diagonal canonical form.
 - (2) (10%) derive the state feedback law u(k) = -Kx(k) for dead-beat response.
- 3. (20%) Consider the characteristic equation of a discrete-time control system given as $z^3 - 1.368z^2 + 0.368(K+1)z + 0.264K = 0$.

Please find the range of K for system stability.

4. (20%) For the backward discrete-equivalent rule ($s \leftarrow \frac{(z-1)}{zT}$), show that

$$\begin{cases} \dot{x}(t) = Ax(t) + Be(t) \\ u(t) = Cx(t) + De(t) \end{cases}$$

can be digitized equivalently in the form of

$$\begin{cases} w(k+1) = \Phi w(k) + \Gamma e(k) \\ u(k) = H w(k) + J e(k) \end{cases}$$

where $\Phi = (I - AT)^{-1}$, $\Gamma = (I - AT)^{-1}BT$.

$$H = C(I - AT)^{-1}, J = D + C(I - AT)^{-1}BT.$$

(Hint: let x(k) = w(k+1).)

5. (20%) Find the pulse transfer function from R(z) to C(z) for the following block diagram.

