

# 國立臺北科技大學

九十八學年第二學期電機系博士班資格考試

## 現代控制理論 試題

第一頁 共二頁

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### 注意事項：

1. 本試題共【4】題，配分共 100 分。
2. 請按順序標明題號作答，不必抄題。
3. 全部答案均須答在試卷答案欄內，否則不予計分。
4. 考試時間：二小時。

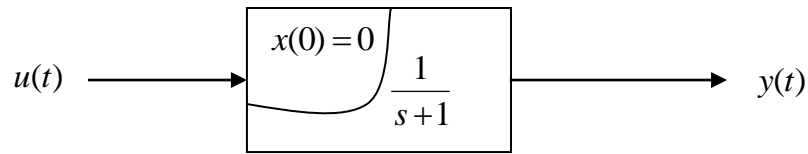
1. (20%) Given a causal system with  $y(t) = g(t) * u(t)$ , where the star denotes convolution. Show that the Laplace transform of  $y(t)$  can be expressed as  $\hat{y}(s) = \hat{g}(s) \cdot \hat{u}(s)$ , where  $\hat{g}(s)$  is the transfer function of the system.
2. (30%) Consider the following linear time-invariant system.

$$\begin{aligned}\dot{x} &= Ax + Bu \\ y &= Cx + Du\end{aligned}$$

Give the discretized system for the case  $u[t] = u[kT]; t \in [kT, (k+1)T), k = 0, 1, 2, \dots$ , where  $u[t]$  is thus a piecewise constant signal. That is, determine the  $F, G, H$ , and  $I$  matrices in the following discrete-time system.

$$\begin{aligned}x[(k+1)T] &= Fx[kT] + Gu[kT] \\ y[kT] &= Hx[kT] + Iu[kT]\end{aligned}$$

3. (20%) Consider the following system



What can you tell about the BIBO stability of the system if you only know that the input signal  $u(t)$  is bounded by 10?

4. (30%) Consider the linear state equation

$$\begin{cases} \dot{x}(t) = A(t)x(t) + B(t)u(t) & ; \quad x(t_0) = x_0 \\ y(t) = C(t)x(t) + D(t)u(t) \end{cases}$$

(a) Give the definition of “controllable on  $[t_0, t_f]$ ”.

(b) Show that the linear state equation is *controllable on  $[t_0, t_f]$*  iff the  $n \times n$  *controllability Gramian*

$$W(t_0, t_f) \equiv \int_{t_0}^{t_f} \Phi(t_0, t) B(t) B'(t) \Phi'(t_0, t) dt$$

is invertible.

(c) Verify whether the following system is controllable or not.

$$\dot{x}(t) = \begin{bmatrix} a_1 & 0 \\ 0 & a_2 \end{bmatrix} x(t) + \begin{bmatrix} b_1(t) \\ b_2(t) \end{bmatrix} u(t) \quad ; \quad t \in [t_0, t_f] \quad \text{where } a_1 \neq a_2$$