## 國立臺北科技大學 九十六學年第二學期電機系博士班資格考試

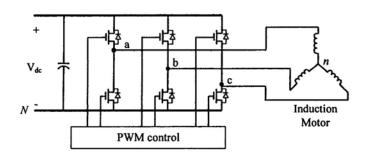
## 電力電子應用技術試題

填學生證號碼

第一頁 共二頁

## 注意事項:

- 本試題共
  題,配分共100分。
  請按順序標明題號作答,不必抄題。
  全部答案均須答在試卷答案欄內,否則不予計分。
- 考試時間:二小時。
- 1. (15%) Give short explanations on the following terminologies: (a) Space voltage vectors, (b) Sine-comparison PWM (SPWM), (c) Space-vector PWM?
- 2. (25%) Following circuit shows a three-phase DC-AC Inverter for induction motors. If the motor is modulated with SPWM, frequency modulation ratio  $m_f >> 1$ , amplitude modulation ratio  $m_a < 1$ , motor phase voltages are balanced and frequency is  $\omega_e$ . Consider only the fundamental components, what is the voltage  $V_{nN}$ ? Give your proof.



3. (25%) If the bus voltage of an DC-AC inverter is  $V_{dc}$ , what is the maximum phase voltage attainable with SPWM without over-modulation? Give your reasoning.

4. (35%) Consider a three-phase, four-poles, induction motor, its parameters are:

Stator resistance  $(r_s)$ 

= 1 ohm

Rotor resistance  $(r_r)$ 

= 2 ohm

Stator self inductance  $(L_s)$ 

 $= 170 \, \mathrm{mH}$ 

Rotor self inductance  $(L_r)$ 

 $= 170 \, \text{mH}$ 

Mutual inductance  $(L_m)$ 

 $= 150 \, \text{mH}$ 

The motor's dq equations in the synchronous rotating frame can be expressed as the following matrix:

$$\begin{bmatrix} V_{qs}^e \\ V_{ds}^e \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} r_s + \sigma L_s p & \omega_e \sigma L_s & \frac{L_m}{L_r} p & \frac{L_m}{L_r} \omega_e \\ -\omega_e \sigma L_s & r_s + \sigma L_s p & -\frac{L_m}{L_r} \omega_e & \frac{L_m}{L_r} p \\ -\frac{L_m}{\tau_r} & 0 & \frac{1}{\tau_r} + p & \omega_e - \omega_r \\ 0 & -\frac{L_m}{\tau_r} & -(\omega_e - \omega_r) & \frac{1}{\tau_r} + p \end{bmatrix} \begin{bmatrix} i_{qs}^e \\ i_{ds}^e \\ \lambda_{qr}^e \\ \lambda_{dr}^e \end{bmatrix}$$

where p=d/dt,  $\tau_r = \frac{L_r}{r_r}$ , and  $\sigma = 1 - \frac{L_m^2}{L_s L_r}$ . The torque equation is

$$T_e = \frac{3}{2} \frac{P}{2} \frac{L_m}{L_r} \left( \lambda_{dr}^e i_{qs}^e - \lambda_{qr}^e i_{ds}^e \right)$$

The motor is operating under <u>rotor flux field orientation</u>, steady state, and its currents are controlled perfectly. If the rotor flux  $\lambda_{dr}^e = 0.5$ Wb,  $\omega_r = 900$  rpm, and output torque = 3 Nm. Answer the following questions:

- a) What is the d-axis current  $i_{ds}^e = ?$
- b) What is the q-axis current  $i_{qs}^e = ?$
- c) What is the rotor's electrical speed  $\omega_e = ?$  (in rad/sec)
- d) Neglect the stator resistance, calculate at what speed (rpm) the motor line voltage is 200 VAC(rms)?