



states (100), (110) and (000). (10%) (Assuming the DC link voltage =  $V_{DC}$ )

5. Illustrate two methods for reducing or blocking the bearing current for three-phase inverter-controller induction motor drives. (10%) And show how these methods can achieve that. (10%)

6. For the induction motor model shown in the equation:

$$\bar{v}_s^e = \bar{i}_s^e R_s + j\omega \bar{\lambda}_s^e + p \bar{\lambda}_s^e$$

$$0 = \bar{i}_r^e R_r + j(\omega - \omega_r) \bar{\lambda}_r^e + p \bar{\lambda}_r^e \quad \text{and with rotor flux oriented control}$$

$$\bar{\lambda}_s^e = L_s \bar{i}_s^e + L_m \bar{i}_r^e$$

$$\bar{\lambda}_r^e = L_m \bar{i}_s^e + L_r \bar{i}_r^e$$

**Derive** the (1). **Slip frequency**, and (2). **Voltage model** of the flux estimator (20%).