國立臺北科技大學

106 學年第二學期電機系博士班資格考試

現代控制理論 試題

第一頁 共二頁

- 注意事項:

 1. 本試題共3題,配分共100分。

 2. 請按順序標明題號作答,不必抄題。

 3. 全部答案均須答在試卷答案欄內,否則不予計分。

 4. 考試時間:二小時。
- 1. Consider the system defined by

$$\dot{\mathbf{x}} = \begin{bmatrix} -1 & 0 & 1 \\ 1 & -2 & 0 \\ 0 & 0 & -3 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$
$$y = \begin{bmatrix} 1 & 1 & 0 \end{bmatrix} \mathbf{x}$$

Transform the system equations into

- a) (10%) controllable canonical form.
- b) (10%) observable canonical form.

2. Consider the system defined by

$$\dot{\mathbf{x}} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

where u(t) is the unit-step function occurring at t = 0, or u(t) = 1(t).

- a) (10%) Find the state-transition matrix, $\Phi(t)$.
- b) (10%) Find the time response, $\mathbf{x}(t)$.
- c) (10%) Simplify the $\mathbf{x}(t)$, if the initial state is zero.

3. Consider the following system

$$\dot{\mathbf{x}} = \begin{bmatrix} 1 & 2 \\ -6 & -12 \end{bmatrix} \mathbf{x} + \begin{bmatrix} -5 \\ 1 \end{bmatrix} u$$
$$y = \begin{bmatrix} 4 & -3 \end{bmatrix} \mathbf{x}$$

- a) (10%) Is it controllable? Please justify your answer.
- b) (10%) Is it observable? Please justify your answer.
- c) (30%) Design a full-state feedback law and an observer by placing the closed-loop system poles at $s_{1,2} = -1 \pm j$ and the observer poles at $s_{1,2} = -12$.